

## 16.5 - Curl and Divergence

In this section we give two new uses of the symbol  $\nabla$ . First, let's properly define it:

Def: The operator  $\nabla$  (pronounced "del") is given

by 
$$\nabla = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$$

( $\nabla = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right\rangle$  in  $\mathbb{R}^2$ ).

We are already familiar with one use of  $\nabla$ :

$$\nabla f = \left\langle \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right\rangle, \quad f = f(x, y, z).$$

(Sometimes  $\nabla f$  is written  $\text{grad } f$ .) Since  $\nabla$

looks like a vector, perhaps we can use it on other types of functions, like vector fields.

Between vectors, we can take dot products & cross products (for vectors in  $\mathbb{R}^3$ ), so:

Def: Given a vector field  $\vec{F}(x,y,z) = \langle P, Q, R \rangle$ , we define:

- the divergence of  $\vec{F}$ :

$$\boxed{\text{div } \vec{F} = \nabla \cdot \vec{F}} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

- the curl of  $\vec{F}$ :

$$\boxed{\text{curl } \vec{F} = \nabla \times \vec{F}} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

$$= \left\langle \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}, \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right\rangle$$

(It is worth pointing out that for a vector field  $\vec{F}(x,y)$  on  $\mathbb{R}^2$ ,  $\text{div } \vec{F}$  can be defined, but  $\text{curl } \vec{F}$  CANNOT!)

Let's do an example before saying more:

Ex: Find the curl and divergence of

$$\vec{F}(x,y,z) = \langle xy^2z^3, x^3yz^2, x^2y^3z \rangle$$

Sol:

$$\text{curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy^2z^3 & x^3yz^2 & x^2y^3z \end{vmatrix}$$

$$= \langle 3x^2y^2z - 2x^3yz, 3xy^2z^2 - 2xy^3z, 3x^2yz^2 - 2xyz^3 \rangle$$

$$= xyz \langle 3xy - 2x^2, 3yz - 2y^2, 3xz - 2z^2 \rangle$$

$$\text{div } \vec{F} = y^2z^3 + x^3z^2 + x^2y^3$$



What exactly are  $\text{div } \vec{F}$  and  $\text{curl } \vec{F}$ ?

Suppose  $\vec{F}$  represents the velocity field of a flowing fluid. The divergence at a point **P** represents the net rate of change of the mass of fluid flowing from **P** per unit volume, i.e.,  $\text{div } \vec{F}(P)$  measures the tendency of the fluid to diverge from **P**. If  $\text{div } \vec{F} = 0$ , we say  $\vec{F}$  is incompressible.

The curl of  $\vec{F}$  at  $P$ , as its name suggests, measures whether particles rotate about an axis at that point, e.g., an eddy or a whirlpool. If they do rotate about an axis at  $P$ , then  $\text{curl } \vec{F}(P)$  gives the direction of the axis, and  $|\text{curl } \vec{F}(P)|$  gives a measure of the speed at which they rotate. If  $\text{curl } \vec{F} = \vec{0}$  at  $P$ , then we say  $\vec{F}$  is irrotational at  $P$ .

Now, div, grad, and curl have some nice relations:

Thm: Let  $\vec{F} = \vec{F}(x,y,z)$  &  $f = f(x,y,z)$  and suppose that  $f$  and the component functions of  $\vec{F}$  are  $C^2$ .

Then: i)  $\text{curl}(\text{grad } f) = \text{curl}(\nabla f) = \nabla \times (\nabla f) = \vec{0}$

ii)  $\text{div}(\text{curl } \vec{F}) = \nabla \cdot (\nabla \times \vec{F}) = \vec{0}$

proof:

$$\text{curl}(\nabla f) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix} = \langle f_{yz} - f_{zy}, f_{xz} - f_{zx}, f_{yx} - f_{xy} \rangle = \vec{0}$$

by Clairaut's theorem.

$$\text{curl } \vec{F} = \left\langle \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}, \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right\rangle$$

$$\text{div}(\text{curl } \vec{F}) = \left( \frac{\partial^2 R}{\partial x \partial y} - \frac{\partial^2 Q}{\partial x \partial z} \right) + \left( \frac{\partial^2 P}{\partial y \partial z} - \frac{\partial^2 R}{\partial y \partial x} \right) + \left( \frac{\partial^2 Q}{\partial z \partial x} - \frac{\partial^2 P}{\partial z \partial y} \right)$$

□

A useful consequence of part (i) is:

Thm: If  $\vec{F} = \langle P, Q, R \rangle$  is defined on a simply connected region, and if  $P, Q, R$  are  $C^1$  on this region, if  $\text{curl } \vec{F} = \vec{0}$ , then  $\vec{F}$  is conservative.

Application of div and curl:

Suppose we are in some region  $\Omega$  with an electric field  $\vec{E}$ , magnetic field  $\vec{B}$ , charge density  $\rho$ , and electric current density  $\vec{J}$ , then

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}, \quad \nabla \cdot \vec{B} = 0, \quad \nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}, \quad \nabla \times \vec{B} = \mu_0 \left( \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

are known as Maxwell's equations.

## Vector Formulations of Green's Theorem

Here we consider  $\vec{F}(x,y,z) = \langle P(x,y), Q(x,y), 0 \rangle$ .

Then,

$$\text{curl } \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & 0 \end{vmatrix} = \langle 0, 0, \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \rangle,$$

so  $(\text{curl } \vec{F}) \cdot \hat{k} = \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}$ . Then the equation in

Green's Theorem reads:

$$\oint_C P dx + Q dy = \oint_C \vec{F} \cdot d\vec{r} = \iint_D (\text{curl } \vec{F}) \cdot \hat{k} dA$$

Recall that  $\oint_C \vec{F} \cdot d\vec{r} = \oint_C (\vec{F} \cdot \vec{T}) ds$ . This means that we are integrating the tangential component of  $\vec{F}$  along  $C$ . What if we wish to integrate the normal component of  $\vec{F}$ ?

Recall, if  $C$  is parametrized by  $\vec{r}(t) = \langle x(t), y(t) \rangle$ ,  $a \leq t \leq b$ , then  $\vec{T}(t) = \frac{1}{|\vec{r}'(t)|} \langle x'(t), y'(t), 0 \rangle$ . You can check that

the outward unit normal to  $C$  is  $\vec{n}(t) = \frac{1}{|\vec{r}'(t)|} \langle y'(t), -x'(t), 0 \rangle$ .

Then,

$$\oint_C (\vec{F} \cdot \vec{n}) ds = \int_a^b (\vec{F} \cdot \vec{n})(t) |\vec{r}'(t)| dt$$

$$= \int_a^b \langle P(\vec{r}(t)), Q(\vec{r}(t)), 0 \rangle \cdot \langle y'(t), -x'(t), 0 \rangle dt$$

$$= \int_a^b (P(\vec{r}(t))y'(t) dt - Q(\vec{r}(t))x'(t) dt)$$

$$= \oint_C P dy - Q dx = \iint_D \left( \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} \right) dA$$

$$= \iint_D (\operatorname{div} \vec{F}) dA$$